Below, we show images of road networks inferred by DeepRoadMapper, our segmentation method, and RoadTracer in the 15 test cities. We overlay the inferred graph (yellow) over ground truth from OpenStreetMap (blue). As in the paper, inferred graphs correspond to thresholds that yield 5% average $F_{\text{error}}$ for RoadTracer and our segmentation approach, and 19% $F_{\text{error}}$ for DeepRoadMapper (as it does not produce results with lower average error). A 5 km by 5 km region is used for testing in each city; we only show a 2 km by 5 km region so that the graphs can more easily be compared with each other on a single page.
Kansas City DeepRoadMapper

Kansas City Segmentation (Ours)

Kansas City RoadTracer
Los Angeles DeepRoadMapper

Los Angeles Segmentation (Ours)

Los Angeles RoadTracer
Tokyo DeepRoadMapper

Tokyo Segmentation (Ours)

Tokyo RoadTracer